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INTEGRATION OF THE LINEAR FILTERING PROBLEM  
BY MEANS OF CANONICAL TRANSFORMATIONS

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Integration of the linear filtering problem by means of canonical transformations\*)

by

Henryk Gzyl\*\*)

#### ABSTRACT

In this note we dwell some more into the formal analogy of quantum mechanics and filtering theory, and we integrate the DMZ-equation by transforming it into a Schroedinger equation that can be integrated in the standard way.

KEY WORDS & PHRASES: *linear filtering-canonical transformations;*  
*harmonic oscillator*

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## 1. INTRODUCTION AND PRELIMINARIES

In this note we exploit the formal analogy between quantum (and classical) mechanics and filtering problems by showing how one can solve the DMZ (Duncan-Mortenson-Zakai) - equation.

$$1.1 \quad \frac{\partial \rho}{\partial t} = \frac{1}{2} \frac{\partial^2 \rho}{\partial x^2} - \frac{\omega^2}{2} x^2 \rho + x \eta \rho$$

where  $\omega$  is a real number and  $\eta$  should be thought of as "Stratonovitch derivative" of the observation process. See [1] or [2] for the filtering background.

Equation (1.1) can be converted, by defining  $\psi(x,t) = \rho(x,ti)$ , into

$$(1.2) \quad i \frac{\partial \psi}{\partial t} = - \frac{1}{2} \frac{\partial^2 \psi}{\partial x^2} + \frac{\omega^2 x^2}{2} \psi + x \xi \psi$$

where  $\xi(t) = - \eta(ti)$ , and (1.2) can be solved using the theory of canonical transformations [3] - [4].

To do this it is easier to start from the classical system, seek the canonical transformation there and then implement it (or realize it) as a unitary change of representation for the quantum system described by (1.2). This is carried out in section 2. In section 3 we rapidly cover the many-dimensional case and in section 4 we make a few comments on how this procedure is related to the work presented in [2]. Disappointingly little seems to come out in this direction.

The results of this paper "simplify" a bit some of the standard computations and allow for a general initial density. Also, they add more to the work of MITTER in [5].

The origin of this paper stems from a conversation with M. Hazewinkel to whom I mentioned that (1.1) should be integrable by means of canonical transformations and he told me what the real questions behind (1.1) were.

## 2. SOLUTION OF 1.2 (and (1.1)).

Consider the mechanical system described by the Hamiltonian

$$(2.1) \quad H(p, x) = \frac{1}{2}(p^2 + \omega^2 x^2) + \xi(t)x.$$

The Hamiltonian equations describing the dynamics of it are

$$(2.2) \quad \frac{dx}{dt} = \frac{\partial H}{\partial p} = p \quad \frac{dp}{dt} = -\frac{\partial H}{\partial x} = -\omega^2 x - \xi(t)$$

and the corresponding quantum evolution equation is (1.2).

Observe now that

$$(2.3) \quad F(x, p, t) = px + pf - \dot{x}f + \phi(t)$$

generates the canonical transformation [3]

$$(2.4) \quad p = \frac{\partial F}{\partial x} = P - \dot{f} \quad Q = \frac{\partial F}{\partial p} = x - \dot{f}$$

changing  $H(p, x)$  into

$$(2.5) \quad \tilde{H}(P, Q) = \frac{1}{2}(P^2 + \omega^2 Q^2)$$

if  $f$  and  $\phi$  are chosen, satisfying zero initial conditions, such that

$$\ddot{f} + \omega^2 f = \xi \quad \frac{\partial \phi}{\partial t} = (\dot{f}^2 - \omega^2 f^2) / 2.$$

In integrating  $\ddot{f} + \omega^2 f = \xi$  one should remember that  $\xi(t)$  is a "Stratonovitch differential". With zero initial conditions

$$f = \frac{1}{\omega} \int_0^t \sin \omega(t-s) \xi(s) ds.$$

In the  $(P, Q)$  coordinates, equations (2.2) and (1.2) become, respectively,

$$(2.6) \quad \frac{dQ}{dt} = P \quad \frac{dP}{dt} = -\omega^2 Q$$

$$(2.7) \quad i \frac{\partial \tilde{\psi}}{\partial t} = -\frac{1}{2} \frac{\partial^2 \tilde{\psi}}{\partial Q^2} + \frac{\omega^2 Q^2}{2} \tilde{\psi}$$

the integration of the first is trivial and that of the second can be found in any text of elementary quantum mechanics. It happens to be

$$\tilde{\psi}(Q, t) = \sum \alpha_n e^{-i\epsilon_n t} \tilde{\psi}_n(Q)$$

where  $\epsilon_n = \omega(n + \frac{1}{2})$  ,  $-\frac{1}{2} \frac{\partial^2 \tilde{\psi}}{\partial Q^2} + \frac{\omega^2 Q^2}{2} \tilde{\psi}_n = \epsilon_n \tilde{\psi}_n$  ,

and  $\alpha_n = (\tilde{\psi}_n, \tilde{\psi}(\cdot, 0)) = \int \tilde{\psi}_n(Q) \tilde{\psi}(\cdot, 0) dQ$  .

Note that

$$\tilde{\psi}_0(Q) = \left(\frac{\omega}{2\pi}\right)^{\frac{1}{2}} \exp -\frac{\omega Q^2}{2}$$

is the eigenfunction corresponding to  $\epsilon_0 = \frac{\omega}{2}$  , a fact that we use below.

All that is needed now is to obtain  $\psi(x, t)$  from  $\tilde{\psi}(Q, t)$ . Well, it so happens (see [9]) that

$$(2.8) \quad \psi(x, t) = \int \langle x|Q \rangle \tilde{\psi}(Q, t) dQ$$

where the transformation function  $\langle x|Q \rangle$  can be obtained from

$$\langle x|P \rangle = (2\pi)^{-\frac{1}{2}} \exp i F(x, P, t)$$

by means of

$$(2.9) \quad \langle x|Q \rangle = \int \langle x|P \rangle e^{-iPQ} \frac{dP}{(2\pi)^{\frac{1}{2}}} = \exp i(\phi - xf) \delta(Q - x - f)$$

which plugged back into (2.8) gives

$$(2.10) \quad \psi(x, t) = \exp i(\phi - xf) \tilde{\psi}(x+f, t)$$

Since the initial condition was originally given for  $\psi(x,0)$ , it is easy to see, from our choice of initial conditions for  $f$  and  $\phi$ , that  $\psi(x,0) = \tilde{\psi}(Q,0)$  and therefore, for arbitrary initial condition, in terms of the eigenfunction expansion, (2.10) reads

$$\psi(x,t) = \sum_n \alpha_n \exp i\{\phi - xf\} - \epsilon_n t \tilde{\psi}_n(x+f)$$

from which the solution to the original equation is

$$(2.11) \quad \rho(x,t) = \psi(t/i) = \sum_n a_n \exp i(\phi(t/i) - xf(t/i)) e^{-\epsilon_n t} \tilde{\psi}_n(x+f(t/i))$$

Also, when  $\psi(x,0) = \psi_0(Q)$ , the expression above reduces to the exponential

$$(2.12) \quad \rho(x,t) = \exp\left\{-\frac{\omega t}{2} + \frac{\omega}{2}(x+f(t/i))^2 + i(\phi(t/i) - xf(t/i))\right\}$$

a rather known result.

Actually, the solution of (2.7) can be written as

$$\tilde{\psi}(Q,t) = \int K(Q,t;Q_0;0) \tilde{\psi}_0(Q_0) dQ_0$$

where

$$K(Q,t;Q_0,t_0) = \left(\frac{m\omega}{2\pi i \sin \omega(t-t_0)}\right)^{1/2} \exp\left\{\frac{im\omega}{2n \sin \omega(t-t_0)} [(Q^2+Q_0^2) \cos \omega(t-t_0) - 2QQ_0]\right\}$$

a result which can be found in [6]. Changing  $t \rightarrow t/i$  and multiplying by  $e^{-t/2}$  one obtains the transition kernel for the oscillator process [7]. In any case  $\rho(x,t)$  can be obtained as follows, first put  $\tilde{\psi}(Q,t/i) = \tilde{\rho}(Q,t)$  where.

$$(2.13) \quad \tilde{\rho}(Q,t) = \int G(Q,t;Q_0) \rho_0(Q_0) dx_0^Q$$

where  $G(Q,t;Q_0) = K(Q,t/i;Q_0)$ . From this one obtains

$$(2.14) \quad \rho(x,t) = \exp i(\phi(t/i) - xf(t/i)) \tilde{\rho}(x+f(t/i),t)$$

and these last two identities express the solution to (1.1) in terms of the

initial conditions in a nicer way than (2.11), but part of the comments above were easier verifiable with it.

### 3. THE MANY-DIMENSIONAL CASE

Consider the filtering problem (see [1] or [2])

$$dx_i = \sum_j \alpha_{ij} dw_j \quad dy_i = \sum_j c_{ij} x_j dt + dv_i$$

for which the DMZ-equation is

$$(3.1) \quad \frac{\partial \rho}{\partial t} = \left\{ \frac{1}{2} \sum_{\omega, k} \alpha_{ik} \alpha_{jt} \frac{\partial^2}{\partial x_i \partial x_j} - \frac{1}{2} \sum_{ijk} c_{kt} c_{kj} x_i x_j \right\} \rho + \sum_i \xi_i x_i \rho$$

where  $\xi_i = \sum_k c_{ik} \frac{dy_k}{dt}$ , and again  $\frac{dy_k}{dt}$  is to be understood formally as a "Stratonovitch derivative".

If we define the matrices  $\mu$  and  $\Omega$  by

$$\mu = \alpha \alpha^+ \quad \Omega = c^+ c$$

we could consider, in analogy with section 2, the mechanical system with Hamiltonian

$$(3.2) \quad H(p, x) = \frac{1}{2} (p^+ \mu p + x^+ \Omega x) + \xi^+ x$$

where vectors are supposed to be column vectors and of course  $^+$  denotes the transpose.

To (3.2) one has associated the classical Hamiltonian equations

$$(3.3) \quad \frac{dx}{dt} = \mu p \quad \frac{dp}{dt} = -\Omega x + \xi$$

and the Schroedinger equation (obtainable from (3.1) by putting  $\psi(x, t) = \rho(x, t_i)$ )

$$(3.4) \quad i \frac{\partial \psi}{\partial t} = -\frac{1}{2} \sum_{ij} \mu_{ij} \frac{\partial^2 \psi}{\partial x_i \partial x_j} + \frac{1}{2} (x^t \Omega x) \psi + (\xi^+ x) \psi.$$



Note first, that the canonical transformation, generated by

$$F = \sum_{ij} (\alpha^+)_{ij}^{-1} P_i x_j \text{ transforms (3.3) and (3.4) into}$$

$$(3.5) \quad \frac{dQ}{dt} = P \quad \frac{dP}{dt} = -\tilde{\Omega} Q - \hat{\xi}$$

and

$$(3.6) \quad i \frac{\partial \tilde{\psi}}{\partial t} = -\frac{1}{2} \sum \frac{\partial^2 \tilde{\psi}}{\partial Q^2} + \frac{1}{2} (Q^+ \tilde{\Omega} Q) \tilde{\psi} + \hat{\xi}^+ Q \tilde{\psi}$$

where

$$\tilde{\psi} = \tilde{\psi}(Q, t), \quad \tilde{\Omega} = \alpha \Omega \alpha^+ \quad \hat{\xi} = \alpha^+ \xi$$

and the associated Hamiltonian is

$$(3.7) \quad H = \frac{1}{2} \{P^+ P + Q^+ \tilde{\Omega} Q\} + \hat{\xi}^+ Q.$$

Let now  $D$  be an orthogonal matrix bringing  $\tilde{\Omega}$  to diagonal form, i.e.

$(D^+ \tilde{\Omega} D)_{ij} = \omega_i^2 \delta_{ij}$ . Let us now consider the canonical transformation generated by  $F' = \sum D_{ji} P_i Q'_j$ . With this transformation (3.7) is transformed into

$$(3.8) \quad H = \sum_i H_i = \sum_i \frac{1}{2} (P_i'^2 + \omega_i^2 (Q_i')^2) + \hat{\xi}_i' Q_i'$$

where

$$\hat{\xi}_i' = \sum D_{ji} \hat{\xi}_j, \quad Q_i' = \sum D_{ji} Q_j, \text{ etc. .}$$

What we have done, is to separate variables in (3.4), preserving the Hamiltonian structure, i.e. (3.4) becomes

$$i \frac{\partial \psi'}{\partial t} = \sum_i \left\{ -\frac{1}{2} \frac{\partial^2 \psi'}{\partial Q_i'^2} + \frac{\omega_i^2}{2} (Q_i')^2 \psi' + \xi_i' Q_i' \psi' \right\}$$

Now proceeding like in section 2, we see that

$$\psi'(Q', t) = \sum_{k_1, \dots, k_n} a(k_1, \dots, k_n) \exp - i \sum_i \epsilon_{k_i} t \prod_1^n \psi'_{k_i}(Q'_i + f_i) \prod \exp i(\phi_i(t) - Q'_i f'_i)$$

with all of the symbols having the same meaning as in section 2 and

$$a(k_1, \dots, k_n) = \int \prod_1^n \psi_{k_i}(Q'_i) \psi'(Q'_1, \dots, Q'_n, 0) dQ'_n.$$

We have leave for the interested reader to supply in the transformation of variables expressing  $\psi(x, t)$  in terms of  $\psi'(Q', t)$  and then making  $t \rightarrow t/i$  to obtain  $\rho(x, t)$ .

#### 4. CONCLUDING COMMENTS

There does not seem to exist an obvious connection between this method and the standard formulation. This is due to the fact that the equation  $i \frac{\partial \psi}{\partial t} = - \frac{1}{2} \frac{\partial^2 \psi}{\partial x^2} + \frac{x^2 \psi}{2}$  or its "associated" diffusion equation  $\frac{\partial \rho}{\partial t} = \frac{\partial^2 \rho}{\partial x^2} - \frac{x^2 \rho}{2}$  does not seem to relate to a filtering problem.

This is rather unfortunate, because all the algebraic structure associated to filtering problems, discussed in [2] for example is lost.

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